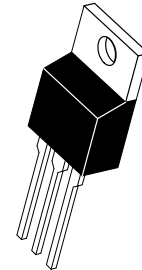


**MJE13009\***

\*Motorola Preferred Device

**12 AMPERE  
NPN SILICON  
POWER TRANSISTOR  
400 VOLTS  
100 WATTS**



**CASE 221A-06  
TO-220AB**

## Designer's™ Data Sheet

# SWITCHMODE Series

# NPN Silicon Power Transistors

The MJE13009 is designed for high-voltage, high-speed power switching inductive circuits where fall time is critical. They are particularly suited for 115 and 220 V switchmode applications such as Switching Regulators, Inverters, Motor Controls, Solenoid/Relay drivers and Deflection circuits.

### SPECIFICATION FEATURES:

- $V_{CEO(sus)}$  400 V and 300 V
- Reverse Bias SOA with Inductive Loads @  $T_C = 100^\circ\text{C}$
- Inductive Switching Matrix 3 to 12 Amp, 25 and  $100^\circ\text{C}$   
...  $t_C @ 8 \text{ A}, 100^\circ\text{C}$  is 120 ns (Typ).
- 700 V Blocking Capability
- SOA and Switching Applications Information.

### MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Collector-Emitter Voltage	$V_{CEO(sus)}$	400	Vdc
Collector-Emitter Voltage	$V_{CEV}$	700	Vdc
Emitter Base Voltage	$V_{EBO}$	9	Vdc
Collector Current — Continuous	$I_C$	12	Adc
— Peak (1)	$I_{CM}$	24	
Base Current — Continuous	$I_B$	6	Adc
— Peak (1)	$I_{BM}$	12	
Emitter Current — Continuous	$I_E$	18	Adc
— Peak (1)	$I_{EM}$	36	
Total Power Dissipation @ $T_A = 25^\circ\text{C}$	$P_D$	2	Watts
Derate above $25^\circ\text{C}$		16	mW/ $^\circ\text{C}$
Total Power Dissipation @ $T_C = 25^\circ\text{C}$	$P_D$	100	Watts
Derate above $25^\circ\text{C}$		800	mW/ $^\circ\text{C}$
Operating and Storage Junction Temperature Range	$T_J, T_{stg}$	-65 to +150	$^\circ\text{C}$

### THERMAL CHARACTERISTICS

Characteristic	Symbol	Max	Unit
Thermal Resistance, Junction to Ambient	$R_{\theta JA}$	62.5	$^\circ\text{C/W}$
Thermal Resistance, Junction to Case	$R_{\theta JC}$	1.25	$^\circ\text{C/W}$
Maximum Lead Temperature for Soldering Purposes: 1/8" from Case for 5 Seconds	$T_L$	275	$^\circ\text{C}$

(1) Pulse Test: Pulse Width = 5 ms, Duty Cycle  $\leq 10\%$ .

**Designer's Data for "Worst Case" Conditions** — The Designer's Data Sheet permits the design of most circuits entirely from the information presented. SOA Limit curves — representing boundaries on device characteristics — are given to facilitate "worst case" design.

**Preferred** devices are Motorola recommended choices for future use and best overall value.

Designer's and SWITCHMODE are trademarks of Motorola, Inc.

REV 2

**ELECTRICAL CHARACTERISTICS** ( $T_C = 25^\circ\text{C}$  unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
<b>*OFF CHARACTERISTICS</b>					
Collector–Emitter Sustaining Voltage ( $I_C = 10\text{ mA}$ , $I_B = 0$ )	$V_{CEO(sus)}$	400	—	—	Vdc
Collector Cutoff Current ( $V_{CEV} = \text{Rated Value}$ , $V_{BE(off)} = 1.5\text{ Vdc}$ ) ( $V_{CEV} = \text{Rated Value}$ , $V_{BE(off)} = 1.5\text{ Vdc}$ , $T_C = 100^\circ\text{C}$ )	$I_{CEV}$	— —	— —	1 5	mAdc
Emitter Cutoff Current ( $V_{EB} = 9\text{ Vdc}$ , $I_C = 0$ )	$I_{EBO}$	—	—	1	mAdc

**SECOND BREAKDOWN**

Second Breakdown Collector Current with base forward biased Clamped Inductive SOA with Base Reverse Biased	$I_{S/b}$ —	See Figure 1 See Figure 2			
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**\*ON CHARACTERISTICS**

DC Current Gain ( $I_C = 5\text{ Adc}$ , $V_{CE} = 5\text{ Vdc}$ ) ( $I_C = 8\text{ Adc}$ , $V_{CE} = 5\text{ Vdc}$ )	$h_{FE}$	8 6	— —	40 30	
Collector–Emitter Saturation Voltage ( $I_C = 5\text{ Adc}$ , $I_B = 1\text{ Adc}$ ) ( $I_C = 8\text{ Adc}$ , $I_B = 1.6\text{ Adc}$ ) ( $I_C = 12\text{ Adc}$ , $I_B = 3\text{ Adc}$ ) ( $I_C = 8\text{ Adc}$ , $I_B = 1.6\text{ Adc}$ , $T_C = 100^\circ\text{C}$ )	$V_{CE(sat)}$	— — — —	— — — —	1 1.5 3 2	Vdc
Base–Emitter Saturation Voltage ( $I_C = 5\text{ Adc}$ , $I_B = 1\text{ Adc}$ ) ( $I_C = 8\text{ Adc}$ , $I_B = 1.6\text{ Adc}$ ) ( $I_C = 8\text{ Adc}$ , $I_B = 1.6\text{ Adc}$ , $T_C = 100^\circ\text{C}$ )	$V_{BE(sat)}$	— — —	— — —	1.2 1.6 1.5	Vdc

**DYNAMIC CHARACTERISTICS**

Current–Gain — Bandwidth Product ( $I_C = 500\text{ mAdc}$ , $V_{CE} = 10\text{ Vdc}$ , $f = 1\text{ MHz}$ )	$f_T$	4	—	—	MHz
Output Capacitance ( $V_{CB} = 10\text{ Vdc}$ , $I_E = 0$ , $f = 0.1\text{ MHz}$ )	$C_{ob}$	—	180	—	pF

**SWITCHING CHARACTERISTICS**

Resistive Load (Table 1)						
Delay Time	$(V_{CC} = 125\text{ Vdc}$ , $I_C = 8\text{ A}$ , $I_{B1} = I_{B2} = 1.6\text{ A}$ , $t_p = 25\text{ }\mu\text{s}$ , Duty Cycle $\leq 1\%$ )	$t_d$	—	0.06	0.1	$\mu\text{s}$
Rise Time		$t_r$	—	0.45	1	$\mu\text{s}$
Storage Time		$t_s$	—	1.3	3	$\mu\text{s}$
Fall Time		$t_f$	—	0.2	0.7	$\mu\text{s}$
Inductive Load, Clamped (Table 1, Figure 13)						
Voltage Storage Time	$(I_C = 8\text{ A}$ , $V_{clamp} = 300\text{ Vdc}$ , $I_{B1} = 1.6\text{ A}$ , $V_{BE(off)} = 5\text{ Vdc}$ , $T_C = 100^\circ\text{C}$ )	$t_{sv}$	—	0.92	2.3	$\mu\text{s}$
Crossover Time		$t_c$	—	0.12	0.7	$\mu\text{s}$

\*Pulse Test: Pulse Width = 300  $\mu\text{s}$ , Duty Cycle = 2%.

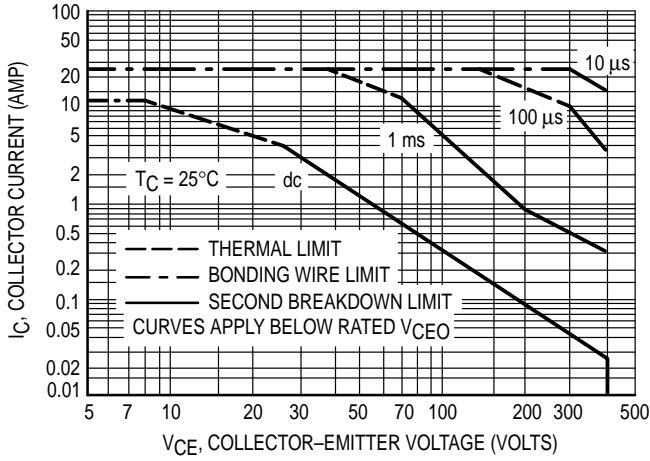


Figure 1. Forward Bias Safe Operating Area

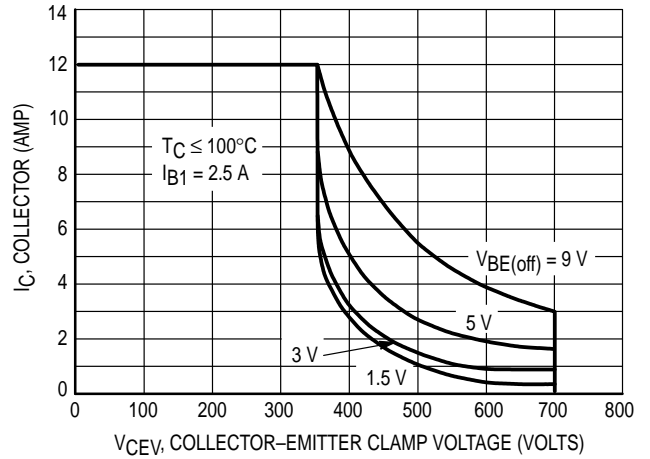


Figure 2. Reverse Bias Switching Safe Operating Area

The Safe Operating Area figures shown in Figures 1 and 2 are specified ratings for these devices under the test conditions shown.

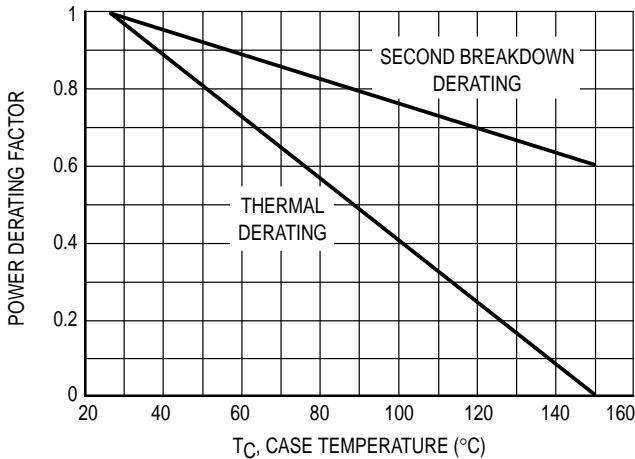


Figure 3. Forward Bias Power Derating

There are two limitations on the power handling ability of a transistor: average junction temperature and second breakdown. Safe operating area curves indicate  $I_C - V_{CE}$  limits of the transistor that must be observed for reliable operation; i.e., the transistor must not be subjected to greater dissipation than the curves indicate.

The data of Figure 1 is based on  $T_C = 25^\circ\text{C}$ ;  $T_{J(pk)}$  is variable depending on power level. Second breakdown pulse limits are valid for duty cycles to 10% but must be derated when  $T_C \geq 25^\circ\text{C}$ . Second breakdown limitations do not derate the same as thermal limitations. Allowable current at the voltages shown on Figure 1 may be found at any case temperature by using the appropriate curve on Figure 3.

$T_{J(pk)}$  may be calculated from the data in Figure 4. At high case temperatures, thermal limitations will reduce the power that can be handled to values less than the limitations imposed by second breakdown. Use of reverse biased safe operating area data (Figure 2) is discussed in the applications information section.

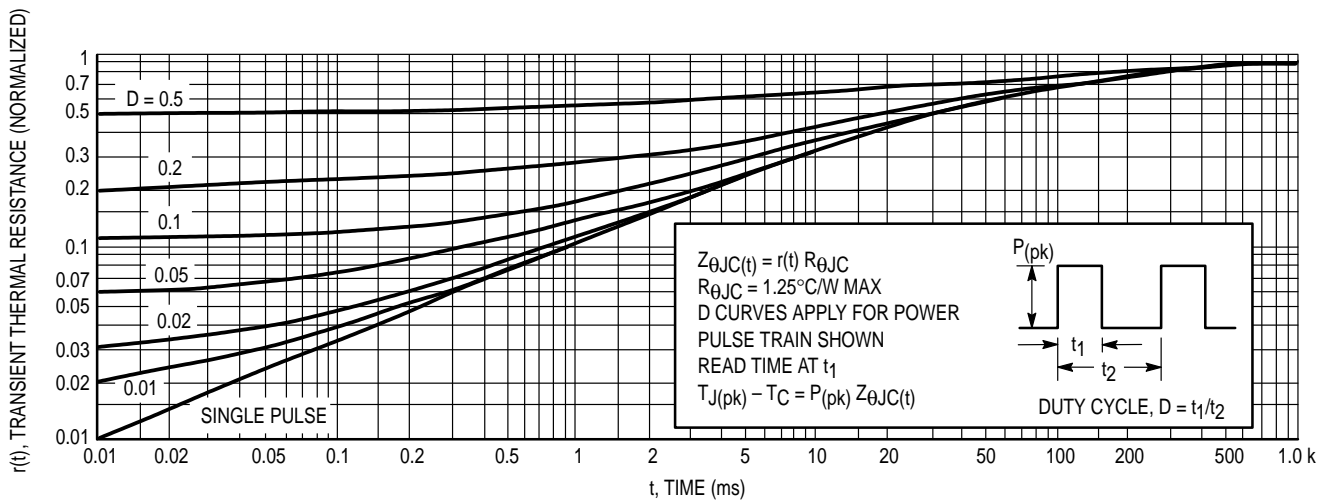


Figure 4. Typical Thermal Response [ $Z_{\theta JC}(t)$ ]

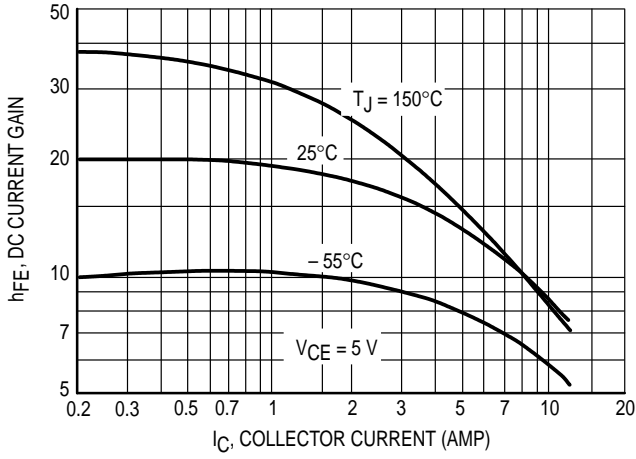


Figure 5. DC Current Gain

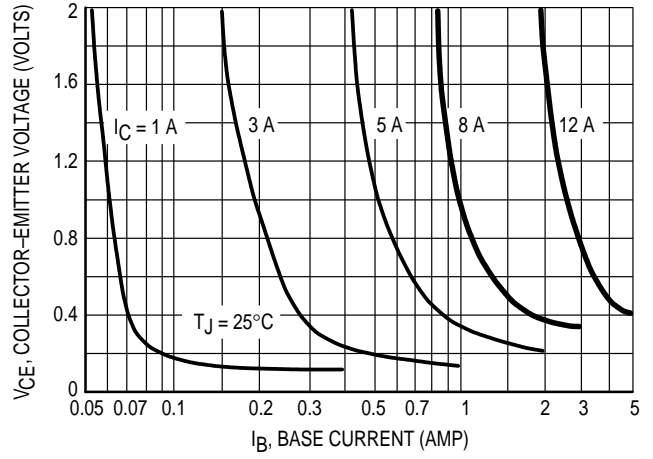


Figure 6. Collector Saturation Region

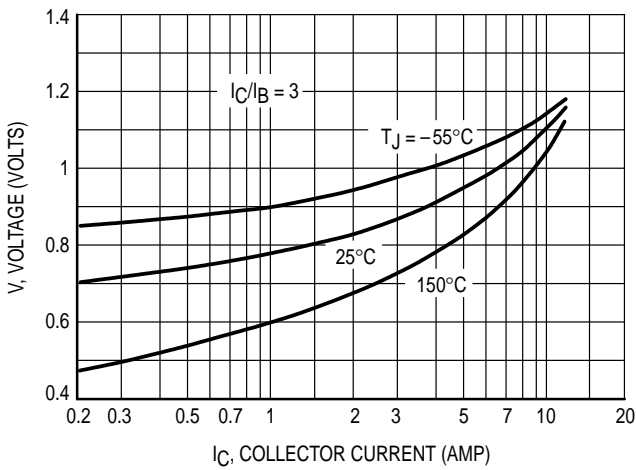


Figure 7. Base-Emitter Saturation Voltage

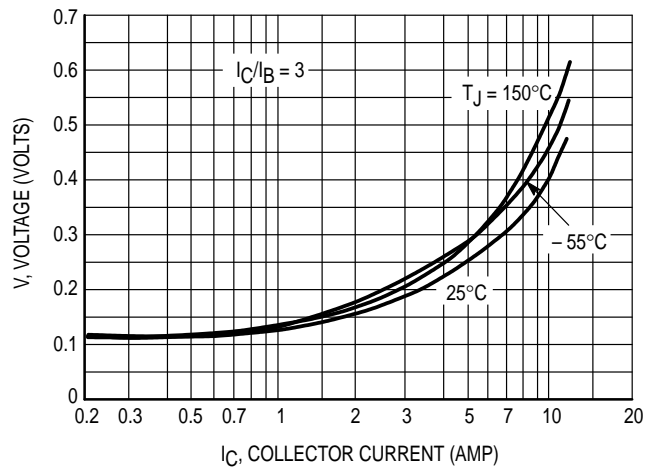


Figure 8. Collector-Emitter Saturation Voltage

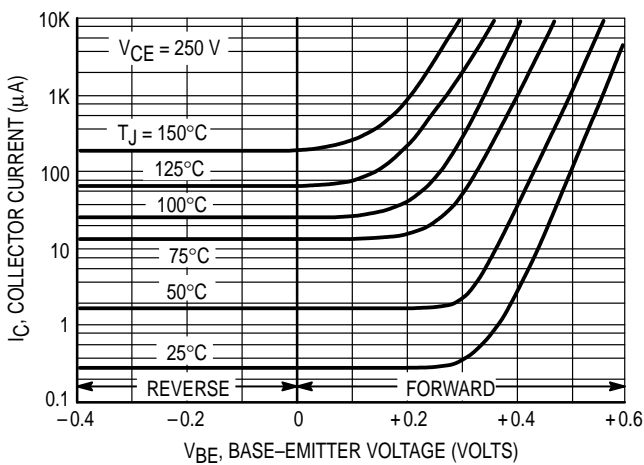


Figure 9. Collector Cutoff Region

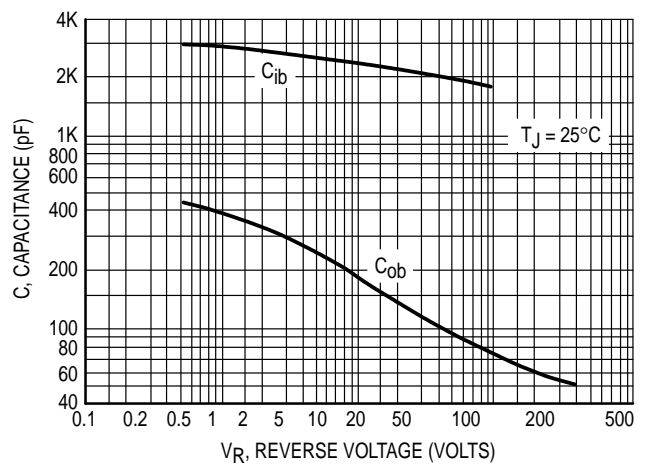


Figure 10. Capacitance



**VOLTAGE REQUIREMENTS (continued)**

In the four application examples (Table 2) load lines are shown in relation to the pulsed forward and reverse biased SOA curves.

In circuits A and D, inductive reactance is clamped by the diodes shown. In circuits B and C the voltage is clamped by the output rectifiers, however, the voltage induced in the primary leakage inductance is not clamped by these diodes and could be large enough to destroy the device. A snubber network or an additional clamp may be required to keep the turn-off load line within the Reverse Bias SOA curve.

Load lines that fall within the pulsed forward biased SOA curve during turn-on and within the reverse bias SOA curve during turn-off are considered safe, with the following assumptions:

- (1) The device thermal limitations are not exceeded.
- (2) The turn-on time does not exceed 10  $\mu$ s (see standard pulsed forward SOA curves in Figure 1).
- (3) The base drive conditions are within the specified limits shown on the Reverse Bias SOA curve (Figure 2).

**CURRENT REQUIREMENTS**

An efficient switching transistor must operate at the required current level with good fall time, high energy handling

capability and low saturation voltage. On this data sheet, these parameters have been specified at 8 amperes which represents typical design conditions for these devices. The current drive requirements are usually dictated by the  $V_{CE(sat)}$  specification because the maximum saturation voltage is specified at a forced gain condition which must be duplicated or exceeded in the application to control the saturation voltage.

**SWITCHING REQUIREMENTS**

In many switching applications, a major portion of the transistor power dissipation occurs during the fall time ( $t_{fi}$ ). For this reason considerable effort is usually devoted to reducing the fall time. The recommended way to accomplish this is to reverse bias the base-emitter junction during turn-off. The reverse biased switching characteristics for inductive loads are discussed in Figure 11 and Table 3 and resistive loads in Figures 13 and 14. Usually the inductive load component will be the dominant factor in SWITCHMODE applications and the inductive switching data will more closely represent the device performance in actual application. The inductive switching characteristics are derived from the same circuit used to specify the reverse biased SOA curves, (See Table 1) providing correlation between test procedures and actual use conditions.

**RESISTIVE SWITCHING PERFORMANCE**

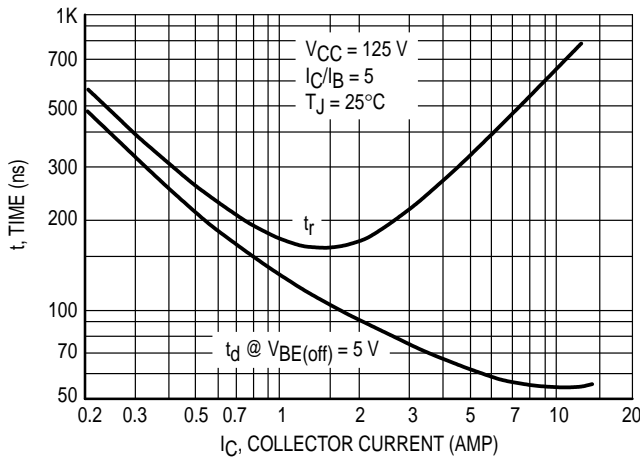


Figure 11. Turn-On Time

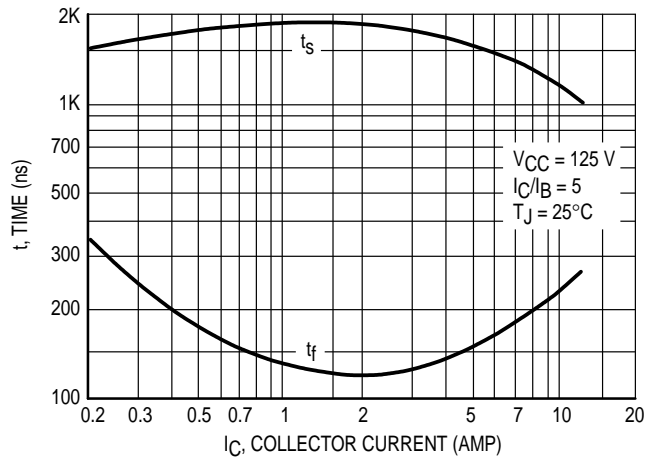


Figure 12. Turn-Off Time

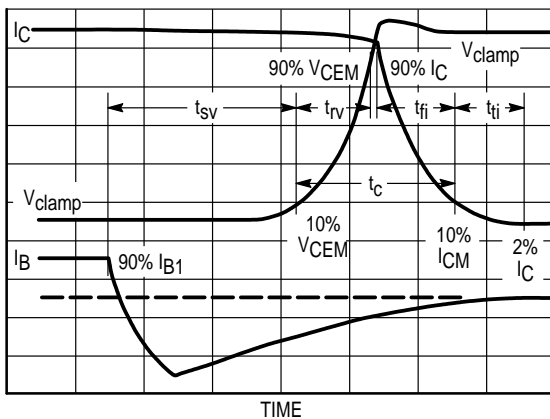


Figure 13. Inductive Switching Measurements

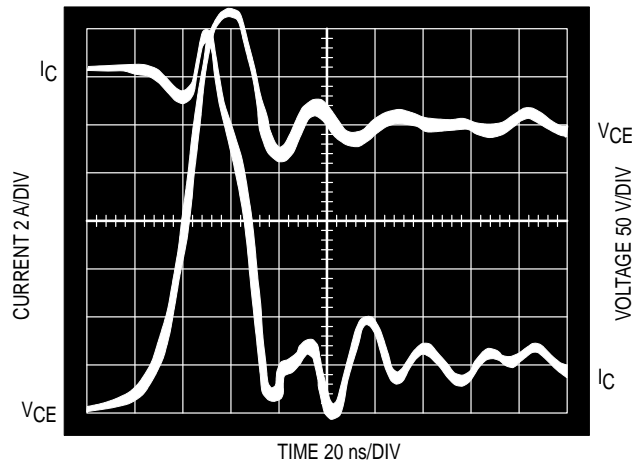


Figure 14. Typical Inductive Switching Waveforms (at 300 V and 12 A with  $I_{B1} = 2.4$  A and  $V_{BE(off)} = 5$  V)

Table 2. Applications Examples of Switching Circuits

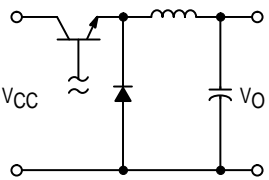
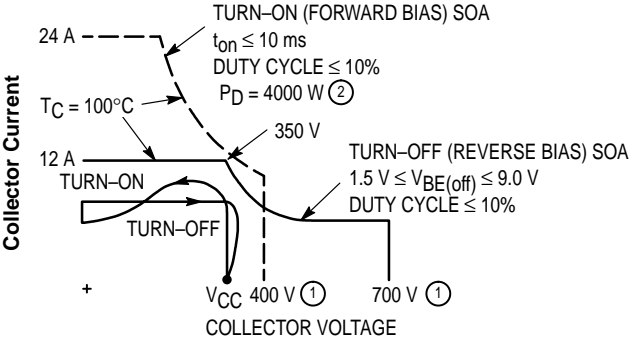
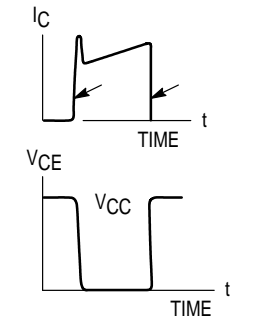
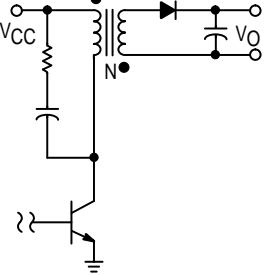
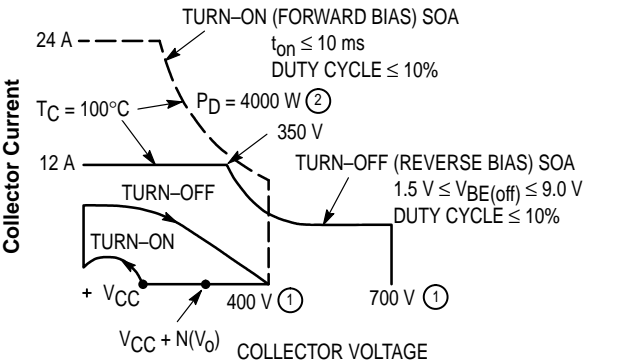
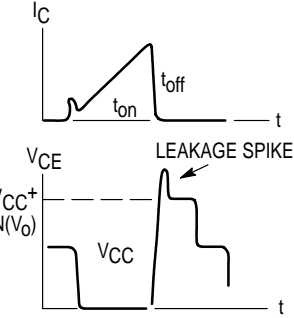
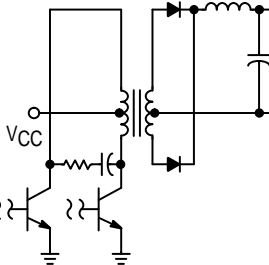
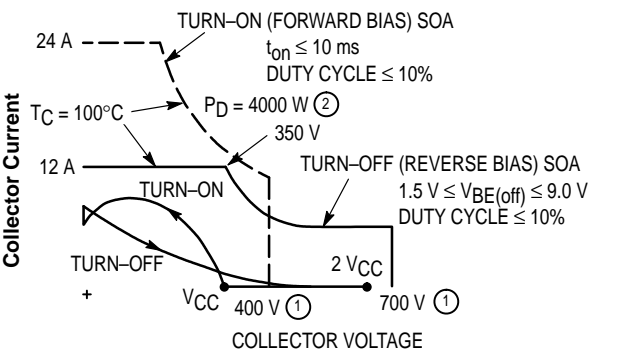
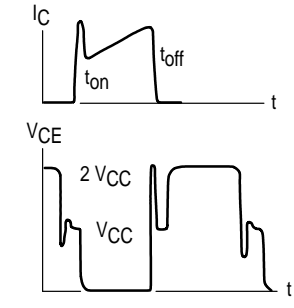
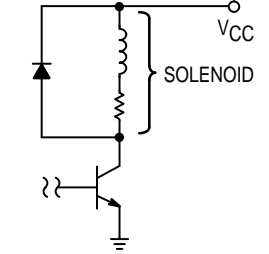
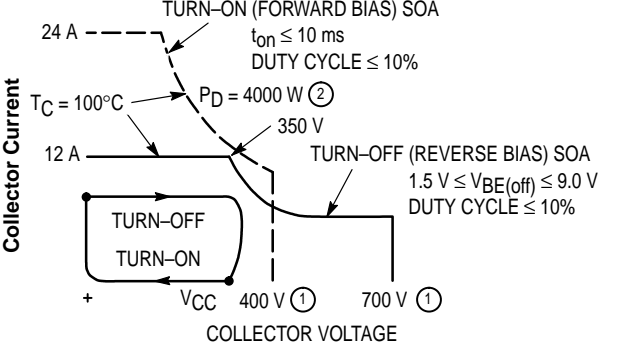
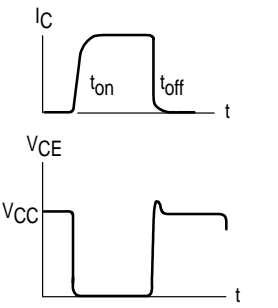
CIRCUIT	LOAD LINE DIAGRAMS	TIME DIAGRAMS
<p><b>SERIES SWITCHING REGULATOR</b></p> 		
<p><b>RINGING CHOKE INVERTER</b></p> 		
<p><b>PUSH-PULL INVERTER/CONVERTER</b></p> 		
<p><b>SOLENOID DRIVER</b></p> 		

Table 3. Typical Inductive Switching Performance

<b>I<sub>C</sub></b> <b>AMP</b>	<b>T<sub>C</sub></b> <b>°C</b>	<b>t<sub>sv</sub></b> <b>ns</b>	<b>t<sub>rv</sub></b> <b>ns</b>	<b>t<sub>fi</sub></b> <b>ns</b>	<b>t<sub>tj</sub></b> <b>ns</b>	<b>t<sub>c</sub></b> <b>ns</b>
3	25	770	100	150	200	240
	100	1000	230	160	200	320
5	25	630	72	26	10	100
	100	820	100	55	30	180
8	25	720	55	27	2	77
	100	920	70	50	8	120
12	25	640	20	17	2	41
	100	800	32	24	4	54

NOTE: All Data recorded In the Inductive Switching Circuit In Table 1.

### SWITCHING TIME NOTES

In resistive switching circuits, rise, fall, and storage times have been defined and apply to both current and voltage waveforms since they are in phase. However, for inductive loads which are common to SWITCHMODE power supplies and hammer drivers, current and voltage waveforms are not in phase. Therefore, separate measurements must be made on each waveform to determine the total switching time. For this reason, the following new terms have been defined.

$t_{sv}$  = Voltage Storage Time, 90%  $I_{B1}$  to 10%  $V_{CEM}$

$t_{rv}$  = Voltage Rise Time, 10–90%  $V_{CEM}$

$t_{fi}$  = Current Fall Time, 90–10%  $I_{CM}$

$t_{tj}$  = Current Tail, 10–2%  $I_{CM}$

$t_c$  = Crossover Time, 10%  $V_{CEM}$  to 10%  $I_{CM}$

An enlarged portion of the turn-off waveforms is shown in Figure 13 to aid in the visual identity of these terms.

For the designer, there is minimal switching loss during storage time and the predominant switching power losses occur during the crossover interval and can be obtained using the standard equation from AN-222:

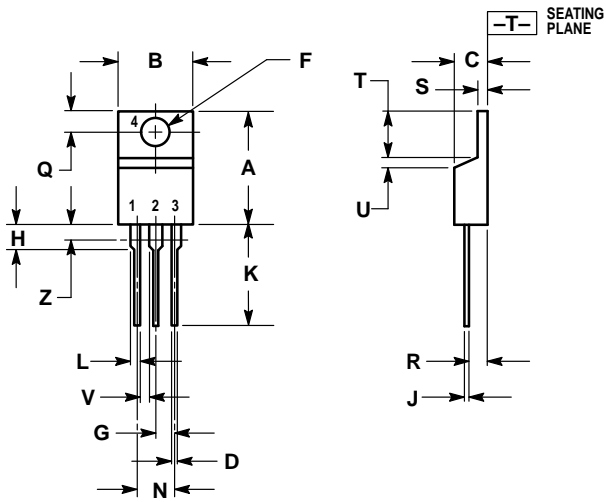
$$P_{SWT} = 1/2 V_{CC} I_C (t_c) f$$

Typical inductive switching waveforms are shown in Figure 14. In general,  $t_{rv} + t_{fi} \approx t_c$ . However, at lower test currents this relationship may not be valid.

As is common with most switching transistors, resistive switching is specified at 25°C and has become a benchmark for designers. However, for designers of high frequency converter circuits, the user oriented specifications which make this a "SWITCHMODE" transistor are the inductive switching speeds ( $t_c$  and  $t_{sv}$ ) which are guaranteed at 100°C.



PACKAGE DIMENSIONS




- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION Z DEFINES A ZONE WHERE ALL BODY AND LEAD IRREGULARITIES ARE ALLOWED.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.570	0.620	14.48	15.75
B	0.380	0.405	9.66	10.28
C	0.160	0.190	4.07	4.82
D	0.025	0.035	0.64	0.88
F	0.142	0.147	3.61	3.73
G	0.095	0.105	2.42	2.66
H	0.110	0.155	2.80	3.93
J	0.018	0.025	0.46	0.64
K	0.500	0.562	12.70	14.27
L	0.045	0.060	1.15	1.52
N	0.190	0.210	4.83	5.33
Q	0.100	0.120	2.54	3.04
R	0.080	0.110	2.04	2.79
S	0.045	0.055	1.15	1.39
T	0.235	0.255	5.97	6.47
U	0.000	0.050	0.00	1.27
V	0.045	—	1.15	—
Z	—	0.080	—	2.04

- STYLE 1:  
 PIN 1. BASE  
 2. COLLECTOR  
 3. EMITTER  
 4. COLLECTOR

CASE 221A-06  
 TO-220AB  
 ISSUE Y

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**MFAX:** RMFAX0@email.sps.mot.com – TOUCHTONE (602) 244-6609  
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51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852-26629298

